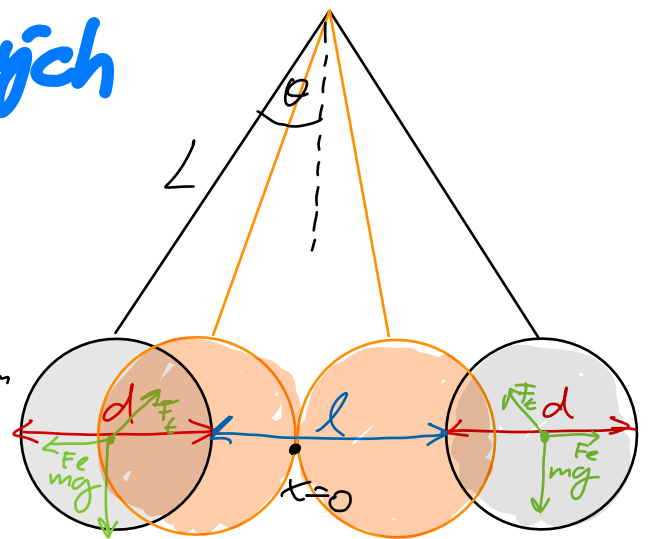
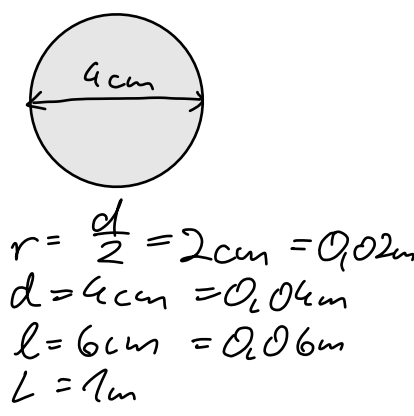
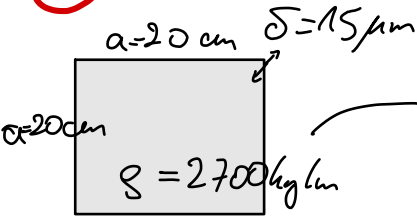


Samuel Jankovych

1



$$m = \rho V = \rho a^2 \delta$$

$$m \approx 1,62 \text{ g}$$

a) Coulomb:

$$F_e = \frac{1}{4\pi\epsilon_0} \frac{q^2}{(l+2r)^2} = \frac{1}{4\pi\epsilon_0} \frac{q^2}{(l+d)^2}$$

$$F = F_g \sin\theta = mg \sin\theta$$

$$F_e = F \Rightarrow mg \sin\theta = \frac{1}{4\pi\epsilon_0} \frac{q^2}{(l+d)^2}$$

$$\frac{r \frac{l}{2}}{L} = \frac{2rel}{2L} = \frac{del}{2L}$$

$$\Rightarrow q = \pm \sqrt{mg \frac{(l+d)^3}{2L} 4\pi\epsilon_0} \approx \pm 29,7 \text{ nC}$$

2 riešenia: bod sú obo
kladne alebo záporne

$$\vec{Q} = \begin{pmatrix} q \\ q \end{pmatrix} = \sum C_{AB} U_B = \vec{C} \vec{U}$$

$$C_{AB} = 4\pi\epsilon_0 \begin{pmatrix} r & -\frac{r^2}{l+d} \\ -\frac{r^2}{l+d} & r \end{pmatrix} = 4\pi\epsilon_0 r \begin{pmatrix} 1 & -\frac{r}{l+d} \\ -\frac{r}{l+d} & 1 \end{pmatrix}$$

$$\Rightarrow \vec{U} = \begin{pmatrix} \varphi \\ \varphi \end{pmatrix} = C_{AB}^{-1} \vec{Q} = \frac{1}{4\pi\epsilon_0 r} \frac{1}{1 - (\frac{r}{l+d})^2} \begin{pmatrix} 1 & \frac{r}{l+d} \\ \frac{r}{l+d} & 1 \end{pmatrix} \begin{pmatrix} q \\ q \end{pmatrix}$$

$$\Rightarrow \varphi = \frac{1}{4\pi\epsilon_0 r} \frac{q}{1 - (\frac{r}{l+d})^2} (1 + \frac{r}{l+d}) = \frac{q}{4\pi\epsilon_0 r} \frac{1}{1 - \frac{r}{l+d}} = \varphi = \frac{q}{4\pi\epsilon_0 r} \frac{l+d}{l+r} = \pm 16,7 \text{ kV}$$

b) minimum potenciálnej energie

$$W_{el} = \frac{1}{2} \sum C_{AB} U_A U_B = \frac{1}{2} \vec{U} \vec{C} \vec{U} \rightarrow \text{zo symetrie } \vec{U} = \begin{pmatrix} \varphi \\ \varphi \end{pmatrix}$$

$$\vec{Q} = \begin{pmatrix} q \\ q \end{pmatrix} = \sum C_{AB} U_B = \vec{C} \vec{U}$$

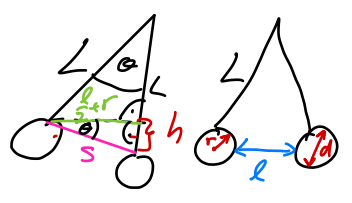
$$C_{AB} = 4\pi\epsilon_0 \begin{pmatrix} r & -\frac{r^2}{l+d} \\ -\frac{r^2}{l+d} & r \end{pmatrix} = 4\pi\epsilon_0 r \begin{pmatrix} 1 & -\frac{r}{l+d} \\ -\frac{r}{l+d} & r \end{pmatrix}$$

$$W_g = 2mgh$$

$$(L-h)^2 + (\frac{l}{2} + r)^2 = L^2$$

$$h'(l) = \frac{l+d}{4\sqrt{L^2 - (\frac{l}{2} + r)^2}}$$

$$h = L - \sqrt{L^2 - (\frac{l}{2} + r)^2}$$



$$W_{\text{tot}} = W_g - W_{el} = 2mgh(l) - 4\pi\epsilon_0 r \varphi^2 \begin{pmatrix} 1 & -\frac{r}{l+d} \\ 1 & r \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix} =$$

$$= 2mgh(l) - 4\pi\epsilon_0 r \varphi^2 \begin{pmatrix} 1 \\ 1 \end{pmatrix} \begin{pmatrix} 1 - \frac{r}{l+d} & 1 - \frac{r}{l+d} \end{pmatrix} = 2mgh(l) - 8\pi\epsilon_0 r \varphi^2 \left(1 - \frac{r}{l+d}\right)$$

$$\frac{\partial W_{\text{tot}}}{\partial l} = 2mg \frac{l+d}{4\sqrt{L^2 - (\frac{l}{2} + r)^2}} - 8\pi\epsilon_0 r \varphi^2 \frac{r}{(l+d)^2} = 0$$

$$\Rightarrow \varphi = \pm \sqrt{\frac{1}{16\pi\epsilon_0} \frac{mg}{\sqrt{L^2 - (\frac{l}{2} + r)^2}} \frac{(l+d)^3}{r^2}} \approx \pm 9,45 \text{ kV}$$

↑ opäť máme dve riešenia

$$\begin{pmatrix} q \\ q \end{pmatrix} = 4\pi\epsilon_0 r \begin{pmatrix} 1 & -\frac{r}{l+d} \\ -\frac{r}{l+d} & r \end{pmatrix} \begin{pmatrix} \varphi \\ \varphi \end{pmatrix} \Rightarrow q = 4\pi\epsilon_0 r \left(1 - \frac{r}{l+d}\right) \varphi$$

$$\Rightarrow q = \pm 4\pi\epsilon_0 r \left(1 - \frac{r}{l+d}\right) \sqrt{\frac{1}{16\pi\epsilon_0} \frac{mg}{\sqrt{L^2 - (\frac{l}{2} + r)^2}} \frac{(l+d)^3}{r^2}} =$$

$$q = \pm \left(1 - \frac{r}{l+d}\right) \sqrt{\pi\epsilon_0 mg \frac{(l+d)^3}{\sqrt{L^2 - (\frac{l}{2} + r)^2}}} \approx \pm 16,83 \text{ nC}$$

→ v prípade bodového náboja je maximum v mieste kde sa nachádza (tým je ∞), teda ak máme vodič, tak maximum bude na jeho povrchu, v prípade dvoch vodičov sa to zmení
 ↳ ostáva zistiť, kde na povrchu bude maximum

$$|E| = q' \left(\frac{1}{y^2 + z^2 + (x - \frac{l}{2} - r)^2} + \frac{1}{y^2 + z^2 + (x + \frac{l}{2} + r)^2} \right) \leftarrow q' = \frac{q}{4\pi\epsilon_0}$$

→ súradnice y a z nemajú vplyv, lebo nie sú obmedzené! BUŇO $y = z = 0$

$$E(x) = q' \left(\frac{1}{(x - \frac{l}{2} - r)^2} + \frac{1}{(x + \frac{l}{2} + r)^2} \right)$$

→ z vety o extrémne vzhľadom k množine staci skúmať hraničné hodnoty intervalov ($\frac{dE}{dx} = 0$ len pre $x = 0$, tým je lok. minimum.)

$$\lim_{x \rightarrow \pm\infty} E(x) = 0$$

$$E\left(\pm \frac{l}{2}\right) = q' \left(\frac{1}{r^2} + \frac{1}{(l+r)^2} \right) \quad E\left(\pm \left(\frac{l}{2} + d\right)\right) = q' \left(\frac{1}{r^2} + \frac{1}{(l+3r)^2} \right)$$

$$E\left(\pm \frac{l}{2}\right) > E\left(\pm \left(\frac{l}{2} + d\right)\right) \Rightarrow E_{\text{max}} = \frac{q}{4\pi\epsilon_0} \left(\frac{1}{r^2} + \frac{1}{(l+2r)^2} \right) \approx 0,79 \frac{\text{MV}}{\text{m}}$$

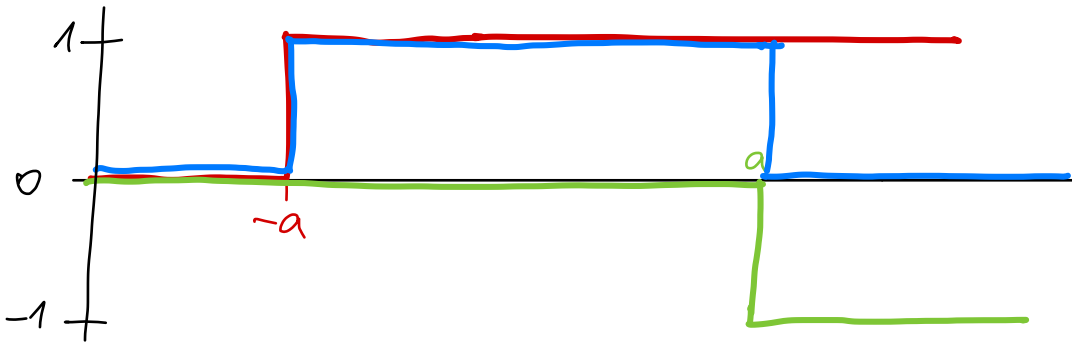
2

$$\phi(x, y, z) = U \int_{-a}^a \frac{\sin^2 \frac{\pi w}{a}}{\sqrt{x^2 + y^2 + (z-w)^2}} dw =$$

$$= U \int_{-a}^a \frac{\sin^2 \frac{\pi z'}{a}}{\sqrt{x^2 + y^2 + (z-z')^2}} dz' = U \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \int_{-a}^a \frac{\sin^2 \frac{\pi z'}{a} \delta(x') \delta(y')}{\sqrt{(x-x')^2 + (y-y')^2 + (z-z')^2}} dx' dy' dz' =$$

$$= \int_V \frac{U \sin^2 \frac{\pi z'}{a} \delta(x') \delta(y') (\Theta(z'+a) - \Theta(z'-a))}{|\vec{r} - \vec{r}'|} d\vec{r}' =$$

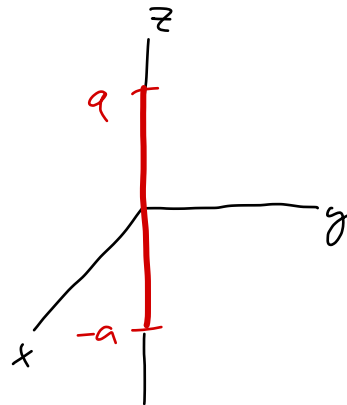
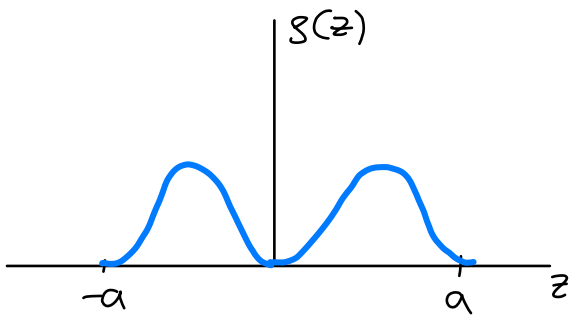
→ Heaviside step func.



$$= \int_V \frac{f(\vec{r}')}{|\vec{r} - \vec{r}'|} d\vec{r}' \quad \Rightarrow \quad f(\vec{r}) = \frac{g(\vec{r})}{4\pi\epsilon_0}$$

$$\Rightarrow g(\vec{r}) = 4\pi\epsilon_0 U \sin^2\left(\frac{\pi z}{a}\right) \delta(x) \delta(y) (\Theta(z+a) - \Theta(z-a))$$

↳ náboj je v tvare úsečky od $-a$ do a , ale hustota není rozložena rovnoměrně

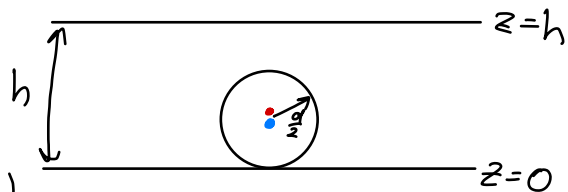


→ celkový náboj je ten integrál

$$Q = \int_{-a}^a 4\pi\epsilon_0 U \sin^2\left(\frac{\pi z}{a}\right) dz = 4\pi\epsilon_0 U a$$

3

$$\vec{E} = \frac{1}{4\pi\epsilon_0} \frac{Q_1}{|\vec{r}-\vec{r}'|^3} \vec{r}' + \frac{1}{4\pi\epsilon_0} \frac{Q_2}{|\vec{r}-\vec{r}''|^3} \vec{r}'' + \frac{U}{h}$$



→ náboje budú na ose $x=y=0 \Rightarrow \vec{r}' = (0,0,z_1)$
 $\vec{r}'' = (0,0,z_2)$

$$\Rightarrow \vec{E} = \frac{1}{4\pi\epsilon_0} \frac{Q_1}{(x^2+y^2+(z-z_1)^2)^{3/2}} \vec{r}' + \frac{1}{4\pi\epsilon_0} \frac{Q_2}{(x^2+y^2+(z-z_2)^2)^{3/2}} \vec{r}'' + \frac{U}{h}$$

$$\Rightarrow \varphi = \frac{1}{4\pi\epsilon_0} \frac{Q_1}{(x^2+y^2+(z-z_1)^2)^{1/2}} + \frac{1}{4\pi\epsilon_0} \frac{Q_2}{(x^2+y^2+(z-z_2)^2)^{1/2}} + \frac{Uz}{h}$$

→ zo symetrie môžeme $y=0$

→ plošnú nábojovú hustotu dostaneme ako $\sigma(\vec{r}_s) = \epsilon_0 \vec{n} \cdot \vec{E}(\vec{r}_s) = \epsilon_0 E_n$

→ zavedieme súradnice $x = R \sin \theta$ $z = R(1 + \cos \theta)$:

$$\varphi = \frac{1}{4\pi\epsilon_0} \frac{Q_1}{(R^2 \sin^2 \theta + R^2 + R^2 \cos^2 \theta - 2Rz_1(1 + \cos \theta) + z_1^2)^{1/2}} + \dots + \frac{UR(1 + \cos \theta)}{h}$$

$$= \frac{Q_1'}{(R^2 + (R-z_1)^2 - 2Rz_1 \cos \theta)^{1/2}} + \frac{Q_2'}{(R^2 + (R-z_2)^2 - 2Rz_2 \cos \theta)^{1/2}} + \frac{UR(1 + \cos \theta)}{h}$$

→ analogicky pre \vec{E} :

$$\vec{E} = \frac{Q_1' \vec{e}_R}{R^2 + (R-z_1)^2 - 2Rz_1 \cos \theta} + \frac{Q_2' \vec{e}_R}{R^2 + (R-z_2)^2 - 2Rz_2 \cos \theta} + \frac{U}{h}$$

$$\Rightarrow E_n(R = \frac{d}{2}) = \vec{E} \cdot \vec{e}_R = \frac{Q_1'}{\frac{d^2}{4} + (\frac{d}{2} - z_1)^2 - d z_1 \cos \theta} + \frac{Q_2'}{\frac{d^2}{4} + (\frac{d}{2} - z_2)^2 - d z_2 \cos \theta} + \frac{U}{h}$$

$$\Rightarrow \sigma(\theta) = \epsilon_0 E_n = \epsilon_0 \vec{E} \cdot \vec{e}_r$$

$$= \frac{1}{4\pi} \left(\frac{Q_1}{\frac{d^2}{4} + (\frac{d}{2} - z_1)^2 - d z_1 \cos \theta} + \frac{Q_2}{\frac{d^2}{4} + (\frac{d}{2} - z_2)^2 - d z_2 \cos \theta} + \frac{U}{h} \right)$$

→ z podm. ekvipotenciály musí platiť $\varphi(R = \frac{d}{2}, \theta = 0) = \varphi(R = \frac{d}{2}, \theta = \frac{2\pi}{3}) = 0$

↳ to nám dá dve riešenia pre Q_1 a Q_2 :

$\text{Phi}[R, \theta] := Q_1 / \text{Sqrt}[R^2 + (R - z_1)^2 - 2 * R * z_1 * \text{Cos}[\theta]] +$
 $Q_2 / \text{Sqrt}[R^2 + (R - z_2)^2 - 2 * R * z_2 * \text{Cos}[\theta]] + U * R * (1 + \text{Cos}[\theta]) / h$
 $\text{Simplify}[\text{Solve}[\{\text{Phi}[d/2, \theta] = 0, \text{Phi}[d/2, 2 * \pi / 3] = 0\}, \{Q_1, Q_2\}]]$

$$Q_1 \rightarrow \frac{d U \sqrt{\frac{d^2}{2} - 2 d z_1 + z_1^2} \sqrt{d^2 - d z_1 + 2 z_1^2} (4 \sqrt{d^2 - 4 d z_2 + 2 z_2^2} - \sqrt{d^2 - d z_2 + 2 z_2^2})}{4 h (\sqrt{d^2 - d z_1 + 2 z_1^2} \sqrt{d^2 - 4 d z_2 + 2 z_2^2} - \sqrt{d^2 - 4 d z_1 + 2 z_1^2} \sqrt{d^2 - d z_2 + 2 z_2^2})}$$

$$Q_2 \rightarrow \frac{d U (4 \sqrt{d^2 - 4 d z_1 + 2 z_1^2} - \sqrt{d^2 - d z_1 + 2 z_1^2}) \sqrt{\frac{d^2}{2} - 2 d z_2 + z_2^2} \sqrt{d^2 - d z_2 + 2 z_2^2}}{4 h (\sqrt{d^2 - d z_1 + 2 z_1^2} \sqrt{d^2 - 4 d z_2 + 2 z_2^2} - \sqrt{d^2 - 4 d z_1 + 2 z_1^2} \sqrt{d^2 - d z_2 + 2 z_2^2})}$$

→ pre tri náboje budeme mať pole

$$\varphi = \frac{1}{4\pi\epsilon_0} \frac{Q_1}{(x^2 + y^2 + (z - z_1)^2)^{\frac{1}{2}}} + \frac{1}{4\pi\epsilon_0} \frac{Q_2}{(x^2 + y^2 + (z - z_2)^2)^{\frac{1}{2}}} + \frac{1}{4\pi\epsilon_0} \frac{Q_3}{(x^2 + y^2 + (z - z_3)^2)^{\frac{1}{2}}} + \frac{U z}{h}$$

→ opäť položíme $y = 0$ a zavedieme $x = R \sin \theta$ $z = R(1 + \cos \theta)$:

$$\varphi = \frac{1}{4\pi\epsilon_0} \left(\frac{Q_1}{\sqrt{(R - z_1 + R \cos \theta)^2 + R^2 \sin^2 \theta}} + \frac{Q_2}{\sqrt{(R - z_2 + R \cos \theta)^2 + R^2 \sin^2 \theta}} + \frac{Q_3}{\sqrt{(R - z_3 + R \cos \theta)^2 + R^2 \sin^2 \theta}} \right) + \frac{U R (1 + \cos \theta)}{h}$$

→ daný potenciál dáme do Mathematicy a vyriešime lin. rovnice:

$$\varphi\left(\frac{d}{2}; 0\right) = 0 \quad \varphi\left(\frac{d}{2}, \frac{2\pi}{3}\right) = 0 \quad \varphi\left(\frac{d}{2}, \frac{\pi}{3}\right) = 0$$

z toho dostaneme hodnoty

$$Q_1 = 209,7 \text{ nC} \quad Q_2 = -217,4 \text{ nC} \quad Q_3 = 2,6 \text{ nC}$$

→ spravnosť hodnôt môžeme overiť aj numerickou minimalizáciou
 on integrálu

$$\int_0^\pi |\varphi\left(\frac{d}{2}; \theta\right)|^2 d\theta, \text{ kde minimalizujeme kvadrát}$$

→ z tejto minimalizácie dostaneme

$$Q_1 = 212,7 \text{ nC} \quad Q_2 = -218,6 \text{ nC} \quad Q_3 = 0,92 \text{ nC}$$

→ hodnoty sú približne rovnaké, ale keďže potenciál
 nespĺňa hraničné podm. tak maximálnym nastavením nájdeme
 správne hodnoty

$$Q_1 = 209 \text{ nC} \quad Q_2 = -218,6 \text{ nC} \quad Q_3 = 0,8 \text{ nC}$$

→ zvolili sme $z_1 = 1,73 \text{ cm}$ $z_2 = 1,77 \text{ cm}$ $z_3 = 1,7 \text{ cm}$

→ skript z Matematika:

```

In[392]:= ClearAll["Global`*"]
Phi[R_, theta_, Q1_, Q2_, Q3_] := Q1/Sqrt[(R - z1 + R Cos[theta])^2 + R^2 Sin[theta]^2] + Q2/Sqrt[(R - z2 + R Cos[theta])^2 + R^2 Sin[theta]^2] +
  Q3/Sqrt[(R - z3 + R Cos[theta])^2 + R^2 Sin[theta]^2] + U * R * (1 + Cos[theta]) / h

s := Solve[{Phi[d/2, theta, Q1, Q2, Q3] == 0, Phi[d/2, 2 * pi/3, Q1, Q2, Q3] == 0, Phi[d/2, pi/3, Q1, Q2, Q3] == 0},
  {Q1, Q2, Q3}, Reals];
q1 := s[[All, 1, 2]][[1]];
q2 := s[[All, 2, 2]][[1]];
q3 := s[[All, 3, 2]][[1]];

In[464]:= U := 8000
d := 3.5
h := 5.5
z1 := 1.73
z2 := 1.77
z3 := 1.70
e := 8.854 * 10^-12
q1 * 4 * pi * e * 10^9 / 100
q2 * 4 * pi * e * 10^9 / 100
q3 * 4 * pi * e * 10^9 / 100
min = NMinimize[NIntegrate[(Phi[d/2, theta, P1 / (4 * pi * e * 10^9 / 100), P2 / (4 * pi * e * 10^9 / 100), P3 / (4 * pi * e * 10^9 / 100)])^2,
  {theta, 0, pi}], {P1, P2, P3}]

```

```

Out[471]= 209.763
Out[472]= -217.36
Out[473]= 2.64879
Out[474]= {0.0717148, {P1 -> 212.728, P2 -> -218.609, P3 -> 0.924725}}

```

```

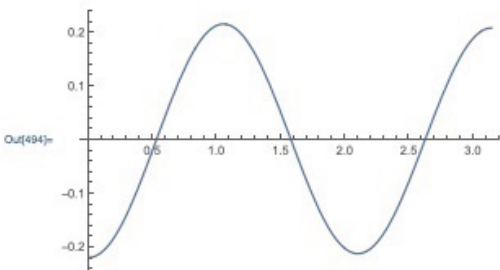
In[491]:= p1 = P1 /. Part[min, 2]
p2 = P2 /. Part[min, 2]
p3 = P3 /. Part[min, 2]
Plot[Phi[d/2, theta, p1 / (4 * pi * e * 10^9 / 100), p2 / (4 * pi * e * 10^9 / 100), p3 / (4 * pi * e * 10^9 / 100)], {theta, 0, pi}]

```

```

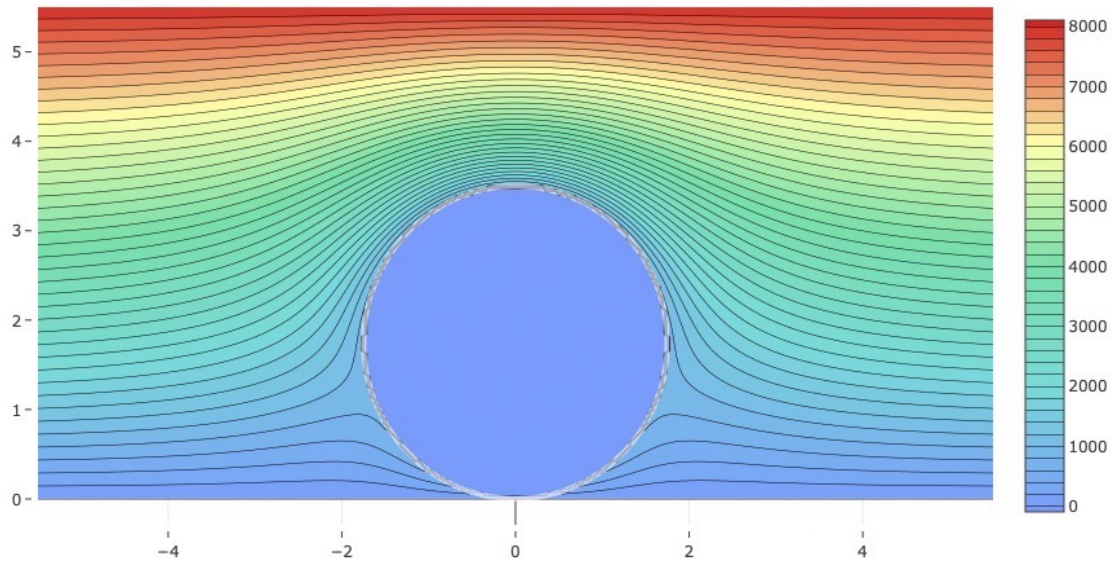
Out[491]= 212.728
Out[492]= -218.609
Out[493]= 0.924725

```



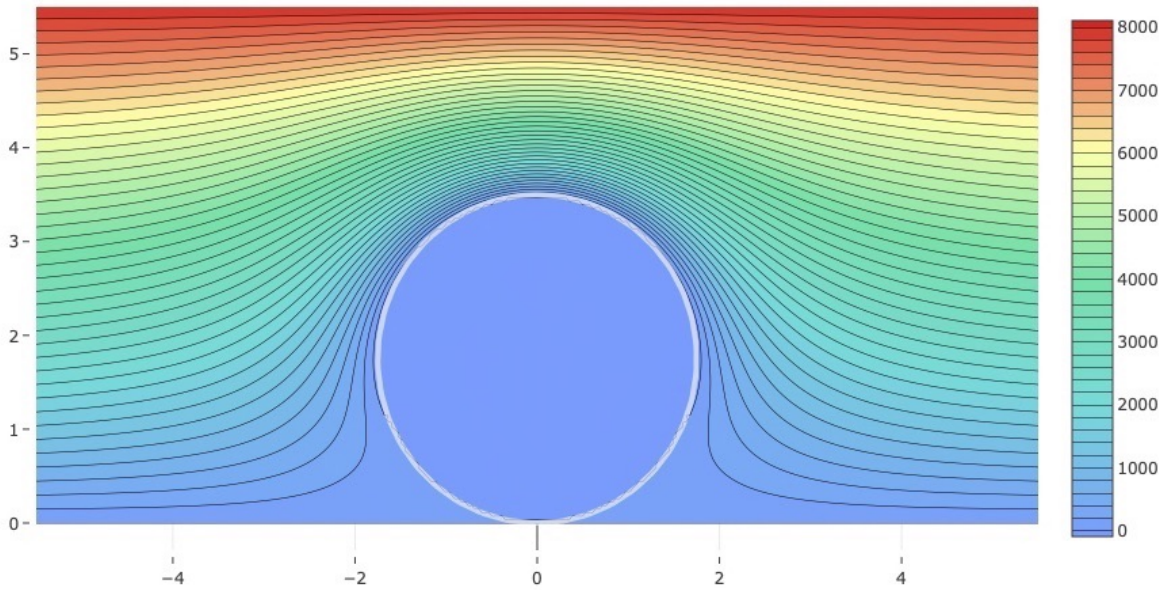
→ graf před manuální minimalizací ($Q_1 = 212,7 \text{ nC}$, $Q_2 = -218,6 \text{ nC}$, $Q_3 = 0,92 \text{ nC}$)

Ekvipotenciály pole elektrod, fiktivních nábojů a jejich obrazů za deskami



→ graf po manuálnej minimalizácii ($Q_1 = 209 \mu\text{C}$, $Q_2 = -218,6 \mu\text{C}$, $Q_3 = 0,8 \mu\text{C}$)

Ekvipotenciálny pole elektrod, fiktívnych nábojů a jejich obrazů za deskami



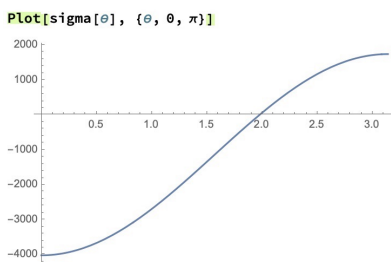
→ plošnú nábojovú hustotu dostaneme zo vzťahu

$$\begin{aligned} \sigma(\theta) &= \epsilon_0 \vec{n} \cdot \vec{E}\left(\frac{d}{2}\right) = \epsilon_0 \vec{e}_r \cdot \vec{E}\left(\frac{d}{2}\right) = \\ &= \frac{1}{4\pi} \left(\frac{Q_1}{\left(\frac{d}{2} - z_1 + \frac{d}{2} \cos \theta\right)^2 + \frac{d^2}{4} \sin^2 \theta} + \frac{Q_2}{\left(\frac{d}{2} - z_2 + \frac{d}{2} \cos \theta\right)^2 + \frac{d^2}{4} \sin^2 \theta} \right. \\ &\quad \left. + \frac{Q_3}{\left(\frac{d}{2} - z_3 + \frac{d}{2} \cos \theta\right)^2 + \frac{d^2}{4} \sin^2 \theta} + \frac{U}{h} \right) \end{aligned}$$

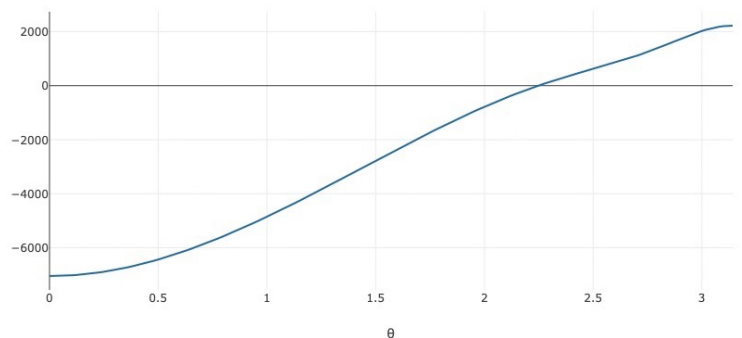
→ graf v dvoch tvaroch (vynesieme iba E_n , tj. $\epsilon_0 = 1$)

Aproximované

```
Q1 := 209 / (4 * pi * e * 10^9 / 100)
Q2 := -218.6 / (4 * pi * e * 10^9 / 100)
Q3 := 0.8 / (4 * pi * e * 10^9 / 100)
R := d / 2
sigma[theta] := Q1 / ((R - z1 + R * Cos[theta])^2 + R^2 * Sin[theta]^2) +
  Q2 / ((R - z2 + R * Cos[theta])^2 + R^2 * Sin[theta]^2) +
  Q3 / ((R - z3 + R * Cos[theta])^2 + R^2 * Sin[theta]^2) + U / h
```



Presnejšie



→ silu tak dostame ako

$$\vec{F} = \int \frac{1}{2} \sigma(\theta) \vec{E} d\theta = \int \frac{1}{2} \epsilon_0 E_n(\theta) \vec{E} d\theta$$

→ zo symetrie vidne $F_x = F_y = 0$

$$|\vec{F}| = F_z = \int \frac{1}{2} \sigma(\theta) E_z d\Omega = \int_0^\pi \frac{\epsilon_0}{2} E_n(\theta) E_z(\theta) 2\pi R^2 \sin\theta d\theta d\varphi$$

$$= \int_0^\pi \pi \epsilon_0 E_n(\theta) E_z(\theta) R^2 \sin\theta d\theta \approx 1,28 \text{ mN}$$

U= 8000 (Napětí na horní elektrodě [V]) d= 3.5 (průměr kuličky [cm]) h= 5.5 (vzdálenost desek [cm])							
Náboj Q₁ Q ₁ = 209 [nC] z ₁ = 1.73 [cm]		Náboj Q₂ Q ₂ = -218.6 [nC] z ₂ = 1.77 [cm]		Náboj Q₃ Q ₃ = 0.8 [nC] z ₃ = 1.7 [cm]			
Nakreslit ekvipotenciály Phi		Funkce f: epsilon*Pi*R*R*sin(theta)*En*Ez Nakreslit f(r=a,theta): Nakreslit f(x,z=0): Nakreslit f(x,z=h):					
θ * (180°/π)	0	30°	60°	90°	120°	150°	180°
Φ(θ)	6.37816707	-49.28209358	-130.73610483	-118.22021578	36.0845453	188.50810506	0
f(θ)	0.00000e+0	1.51542e-3	8.20652e-4	-1.90147e-5	-1.47066e-5	-3.01298e-5	-5.14840e-20
∫ ^θ f(θ') dθ'	0.00000e+0	4.83310e-4	1.16468e-3	1.33056e-3	1.30607e-3	1.30171e-3	1.27818e-3
x	-10 h	-3 h	-h	0	+h	+3h	+10h
f(x,z=h)	-1.79813e-4	-1.75779e-4	-1.71770e-4	0.00000e+0	-1.71770e-4	-1.75779e-4	-1.79813e-4
∫ ^x f(x',z=h) dx'	9.74951e-3	2.86340e-3	9.75911e-4	0.00000e+0	-9.75911e-4	-2.86340e-3	-9.74951e-3
f(x,z=h)	1.80140e-4	1.79196e-4	1.46107e-4	5.14840e-20	1.46107e-4	1.79196e-4	1.80140e-4
∫ ^x f(x',z=0) dx'	-9.18012e-3	-2.25294e-3	-3.43776e-4	0.00000e+0	3.43776e-4	2.25294e-3	9.18012e-3

